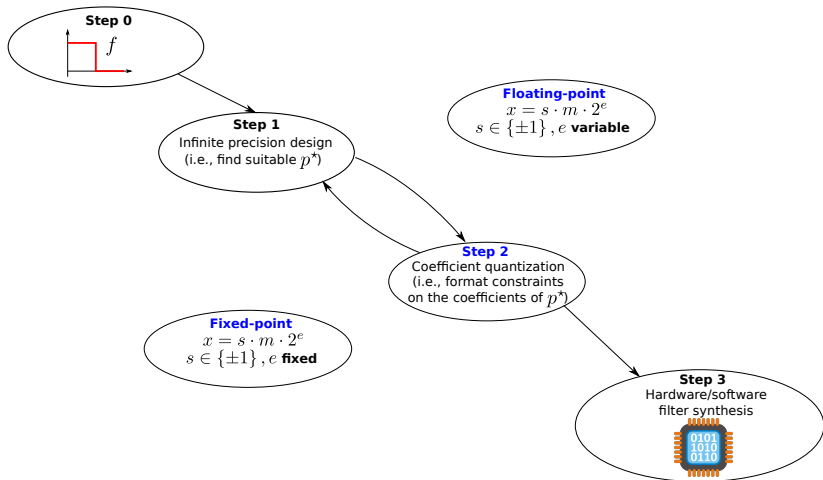


# A lattice basis reduction approach for the design of finite wordlength FIR filters

**Silviu Filip**

Mathematical Institute, Numerical Analysis Group, University of Oxford  
joint work with **Nicolas Brisebarre** and **Guillaume Hanrot**

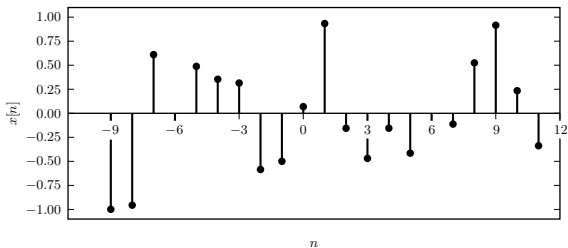
Rencontres Arithmétiques de l'Informatique Mathématique (RAIM)  
Lyon, October 24-26, 2017



Digital signal processing = the study of discrete-time signals

Usual notation:  $x[n], n \in \mathbb{Z}$

Example:



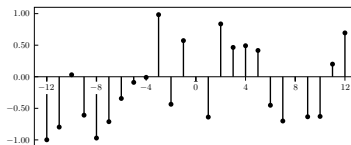
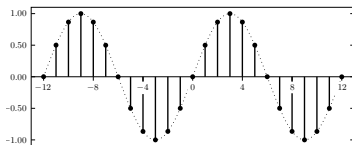
→ measured data = signals:

- temperature readings;
- content of data packets (in network transmissions);
- stock price changes;
- etc.

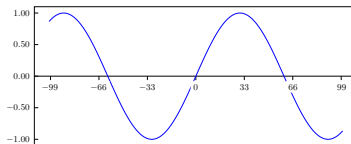
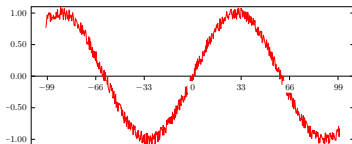
How do we extract information from signals?

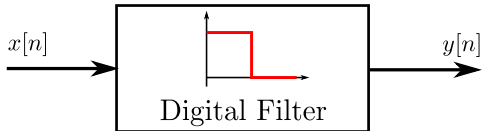
Examples:

1. Periodicity?

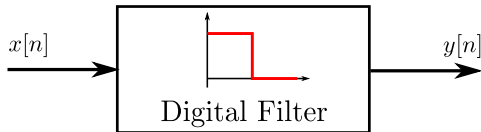


2. Noise?



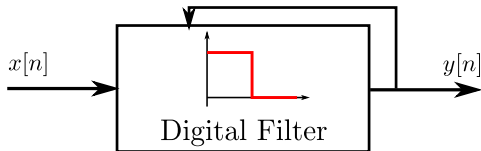


→ we get two categories of linear filters



$$y[n] = b_0 x[n] + \sum_{k=1}^N b_k x[n-k]$$

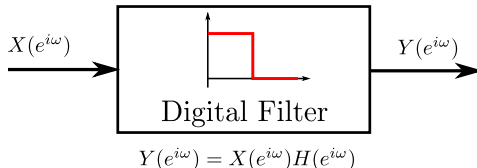
- we get two categories of linear filters
- finite impulse response (**FIR**) filters



$$y[n] = b_0 x[n] + \sum_{k=1}^N b_k x[n-k] - \sum_{k=1}^M a_k y[n-k]$$

→ we get two categories of linear filters

- finite impulse response (**FIR**) filters
- infinite impulse response (**IIR**) filters

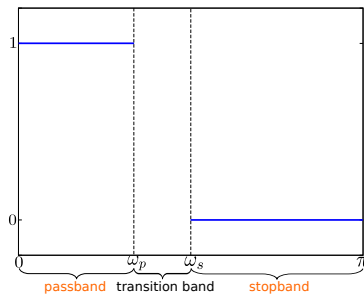


- we get two categories of linear filters
  - finite impulse response (**FIR**) filters  
 $H$  is a polynomial
  - infinite impulse response (**IIR**) filters  
 $H$  is a rational function
- convenient to work in the **frequency** domain
- **focus** on FIR filters (with linear phase)

# FIR filters: Chebyshev approximation

Input:

- degree  $n$
- approximation bands  $\Omega \subseteq [0, \pi]$
- ideal response  $D(\omega)$ ,  $\omega \in \Omega$



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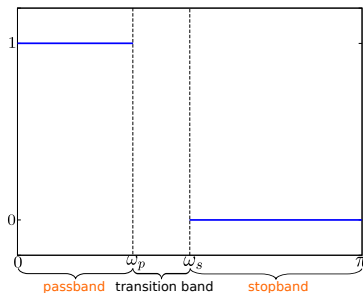
Output:

$$H(e^{i\omega}) = \sum_{k=0}^n h_k \cos(k\omega) = \sum_{k=0}^n h_k T_k(\cos(\omega)),$$

s. t.

$$\delta = \max_{\omega \in \Omega} |D(\omega) - H(e^{i\omega})|$$

is **minimal**



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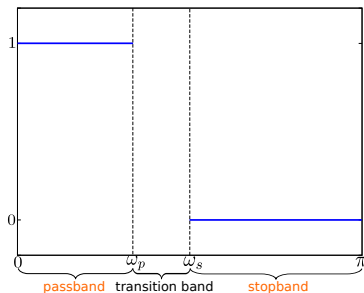
Output:

$$H(e^{i\omega}) = \sum_{k=0}^n h_k \cos(k\omega) = \sum_{k=0}^n h_k \underbrace{T_k(\cos(\omega))}_{=x},$$

s. t.

$$\delta = \max_{\omega \in \Omega} \underbrace{|D(\omega) - H(e^{i\omega})|}_{f(x)} = \max_{x \in X} \underbrace{\rho^*(x)}_{p^*(x)}$$

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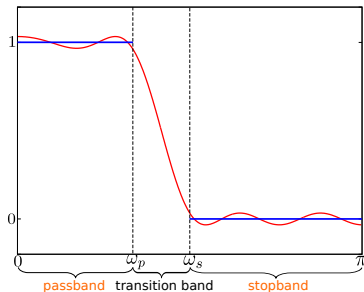
$$H(e^{j\omega}) = \sum_{k=0}^n h_k \cos(k\omega) = \sum_{k=0}^n h_k \underbrace{T_k(\cos(\omega))}_{=x},$$

s. t.

$$\delta = \max_{x \in X} | \underbrace{D(\omega)}_{f(x)} - \underbrace{H(e^{j\omega})}_{p^*(x)} |$$

is minimal

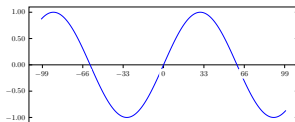
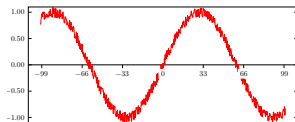
Where is this filter useful?



Example:

→ degree  $n = 8$

$$p^*(x) = \sum_{k=0}^8 h_k T_k(x)$$

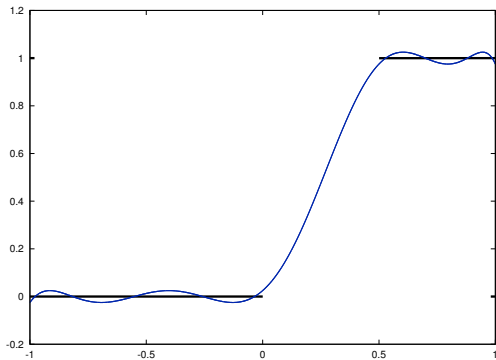


Floating point arithmetic is sometimes expensive (*i.e.*, in embedded systems)

→ use fixed-point arithmetic (scaled integers in a certain range)

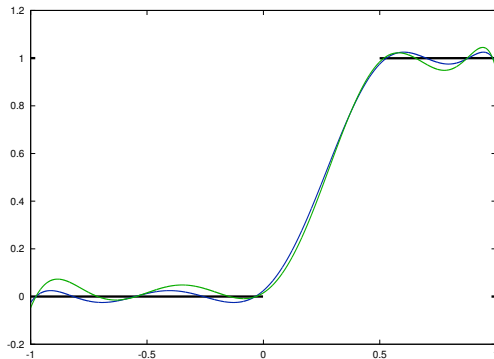
**Two main reasons:** small price + fast hardware

→ frequent for signal processing applications



$$p^*(x) = \frac{a_0}{2} T_0(x) + \sum_{k=1}^9 a_k T_k(x), \delta \simeq 0.0249$$

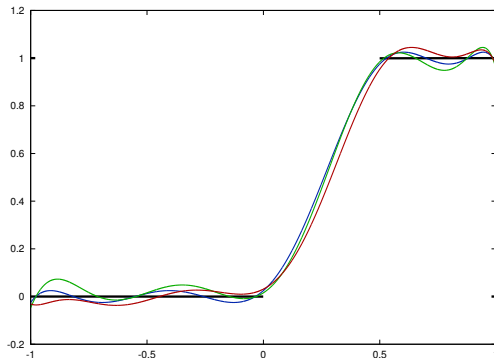
→ 7-bit coefficients:  $a_k = \frac{m_k}{2^5}$ ,  $m_k \in \mathbb{Z} \cap [-63, 63]$ ,  $k = 0, \dots, 9$ .



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**Naive approach** Simple rounding of the  $a_k \in \mathbb{R}$  result:  $\delta \simeq 0.0731$



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**Naive approach** Simple rounding of the  $a_k \in \mathbb{R}$  result:  $\delta \simeq 0.0731$

**Optimal quantization**  $\delta \simeq 0.0468$

→ take  $\varphi_0(x) = \frac{T_0(x)}{2^6}, \varphi_1(x) = \frac{T_1(x)}{2^5}, \dots, \varphi_9(x) = \frac{T_9(x)}{2^5}$

→ **want** to solve

minimize  $\delta$

subject to  $\sum_{k=0}^9 m_k \varphi_k(x) - f(x) \leq \delta, x \in X,$

$$f(x) - \sum_{k=0}^9 m_k \varphi_k(x) \leq \delta, x \in X,$$

$$\delta > 0, \quad m_k \in \mathbb{Z} \cap [-63, 63], k = 0, \dots, 9.$$

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→ **actually** solve

$$\begin{aligned}
 &\text{minimize} && \delta \\
 &\text{subject to} && \sum_{k=0}^9 m_k \varphi_k(x) - f(x) \leq \delta, x \in X_d, \\
 & && f(x) - \sum_{k=0}^9 m_k \varphi_k(x) \leq \delta, x \in X_d, \\
 & && \delta > 0, \quad m_k \in \mathbb{Z} \cap [-63, 63], k = 0, \dots, 9.
 \end{aligned}$$

$X \rightarrow X_d$  discrete: mixed-integer linear programming

**Other heuristic approaches:**

→ MATLAB uses a stochastic-based method

→ with no format constraints, **interpolation** at well-placed nodes works well

Why not do something similar here?

→ take  $x_0 < x_1 < \dots < x_n$ , all from  $X$  and find appropriate  $m_k \in \mathbb{Z}$  s.t.

$$\sum_{i=0}^n m_k \begin{bmatrix} \varphi_k(x_0) \\ \varphi_k(x_1) \\ \vdots \\ \varphi_k(x_n) \end{bmatrix} \approx \begin{bmatrix} f(x_0) \\ f(x_1) \\ \vdots \\ f(x_n) \end{bmatrix}$$

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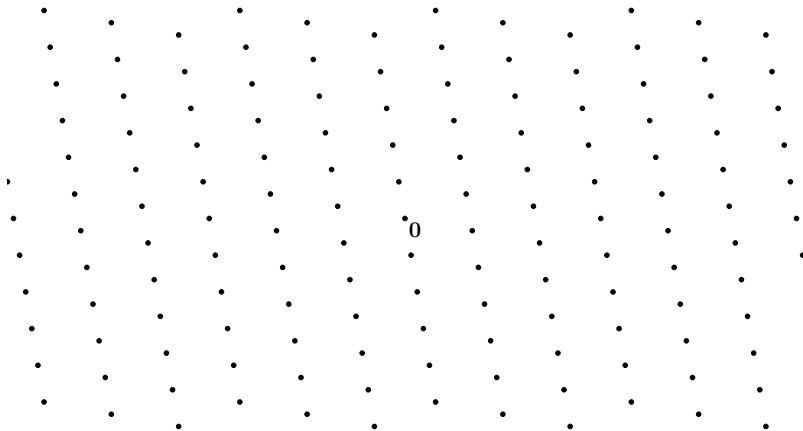
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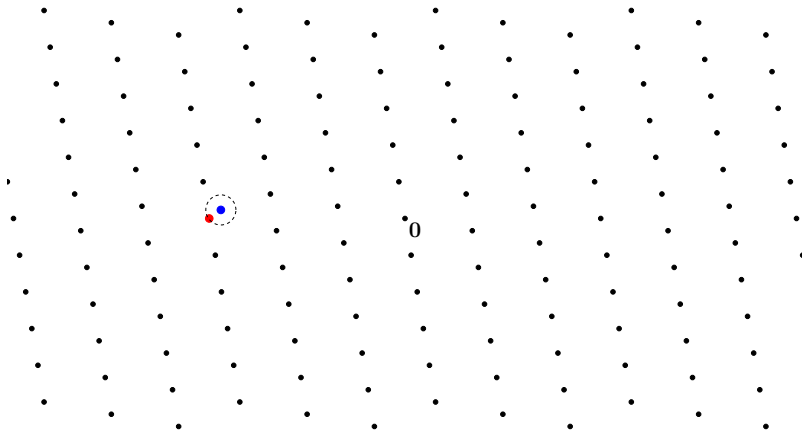
**How can we solve this pseudo interpolation problem?**

→ state it as an Euclidean lattice problem

→ consider the case  $n = 1$

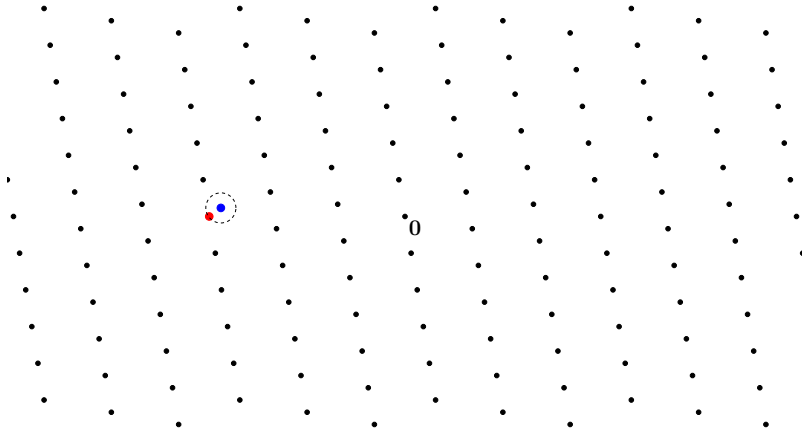


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NP-hard problem in general.

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NP-hard problem in general. Efficient algorithms: approximate solutions.

→ problem in Euclidean lattice theory:

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→ use fast, approximate solvers:

- **LLL** algorithm [Lenstra, Lenstra & Lovász 1982]
- Kannan embedding [Kannan 1987]

→ on the toy example, we get the **optimal** result

## What interpolation points do we use?

$$\mathbf{x} = \{x_0, \dots, x_n\}$$

$$\mathbb{R}_n[x] = \text{span}_{\mathbb{R}} \{\varphi_0, \dots, \varphi_n\} \quad (\varphi_k(x) = T_k(x))$$

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→ Lagrange interpolation at  $\mathbf{x}$ :

$$\mathcal{L}_{\mathbf{x}} f(x) = \sum_{i=0}^n f(x_i) \underbrace{\frac{\det V(x_0, \dots, x_{i-1}, x, x_{i+1}, \dots, x_n)}{\det V(x_0, \dots, x_{i-1}, x_i, x_{i+1}, \dots, x_n)}}_{\ell_i(x)}$$

where  $V(x_0, \dots, x_n) = [v_{ij}] := [\varphi_j(x_i)]$ .

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$$\Lambda_{X, \mathbf{x}} = \max_{x \in X} \sum_{i=0}^n |\ell_i(x)|$$

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→ measures **quality** of  $\mathbf{x}$  for doing interpolation:

$$\forall f \in \mathcal{C}(X), \|f - \mathcal{L}_{\mathbf{x}} f\|_{\infty, X} \leq (1 + \Lambda_{X,\mathbf{x}}) \|f - p^*\|_{\infty, X}$$

→ if  $X = [-1, 1]$ , take Chebyshev nodes

$$x_k = \cos\left(\frac{(n-k)\pi}{n}\right), \quad k = 0, \dots, n$$

$$\Lambda_{X,x} = \mathcal{O}(\log n)$$

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## Approach:

→ replace  $X$  with a **suitable** discretization  $X_n$

→  $x \subset X_n$  generates max volume  $(n+1) \times (n+1)$  submatrix of  $V(X_n)$

→ NP-hard problem [Çivril & Magdon-Ismail, 2009]

→ greedy algorithm based on QR factorization [Sommariva & Vianello, 2010]

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$$\Lambda_{X,x} = \mathcal{O}_X(n \log n)$$

→ our finite wordlength polynomial  $p$  satisfies:

$$\|f - p\|_{\infty, X} \leq (1 + \Lambda_{X,x}) \|f - p_{opt}\|_{\infty, X} + \Lambda_{X,x} \delta$$

where:

- $\delta = \max_{0 \leq k \leq n} |p(z_k) - f(z_k)|$
- $p_{opt}$  is an optimal solution

→ specification:

$$X = [-1, \cos(0.84\pi)] \cup [\cos(0.68\pi), \cos(0.4\pi)] \cup [\cos(0.24\pi), 1],$$

$$f(x) = \begin{cases} 1, & x \in [-1, \cos(0.84\pi)] \cup [\cos(0.24\pi), 1] \\ 0, & x \in [\cos(0.68\pi), \cos(0.4\pi)] \end{cases}$$

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| $n/\text{bit size}$ | Minimax<br>$\delta_{\text{minimax}}$ | Optimal<br>$\delta_{\text{opt}}$ | Naive rounding<br>$\delta_{\text{naive}}$ | Lattice-based<br>$\delta_{\text{lattice}}$ |
|---------------------|--------------------------------------|----------------------------------|-------------------------------------------|--------------------------------------------|
| 17/8                | $2.631 \cdot 10^{-3}$                | 0.01787                          | 0.04687                                   | 0.01787                                    |
| 22/8                | $6.709 \cdot 10^{-4}$                | 0.01609                          | 0.03046                                   | 0.01609                                    |
| 62/21 <sup>†</sup>  | $1.278 \cdot 10^{-8}$                | $1.564 \cdot 10^{-6}$            | $8.203 \cdot 10^{-6}$                     | $1.621 \cdot 10^{-6}$                      |

- efficient method for obtaining quasi-optimal fixed point FIR filters
- very scalable ( $n = 100$  problems usually take  $< 10$  seconds)
- available as an open source C++ library:  
<https://github.com/sfilip/fquantizer>

**Future work:**

- low-complexity coefficients
- IIR filters with fixed-point coefficients

Thank you!