

# Reliable verification of digital implemented filters against frequency specifications

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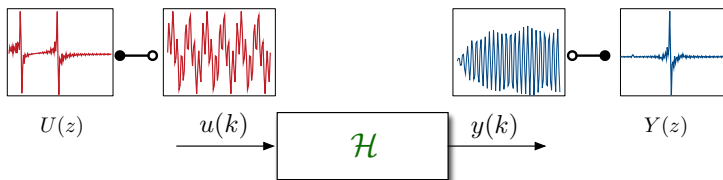
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# Linear Time-Invariant Digital Filters

- Time domain



- Frequency domain

$$H(z) = \frac{\sum_{i=0}^n b_i z^{-i}}{\sum_{i=0}^n a_i z^{-i}}, \quad z \in \mathbb{C}, \quad a_i, b_i \in \mathbb{R}$$

# Frequency specifications

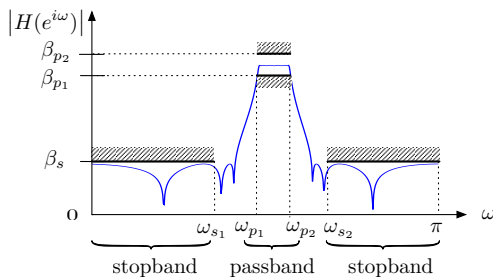
Frequency response ( $z = e^{j\omega}$ )

$$H(e^{j\omega}) = \underbrace{|H(e^{j\omega})|}_{\text{magnitude}} e^{\underbrace{\angle H(e^{j\omega})}_{\text{phase}}}$$

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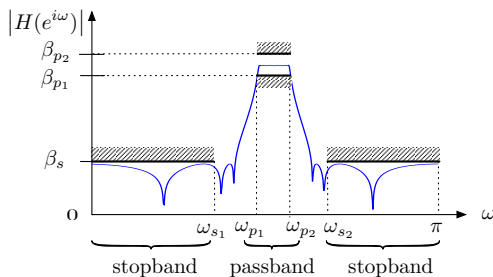
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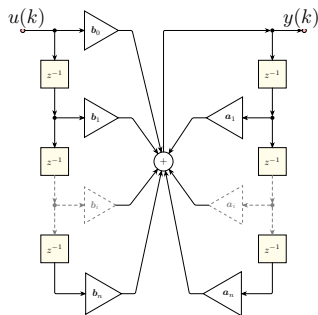
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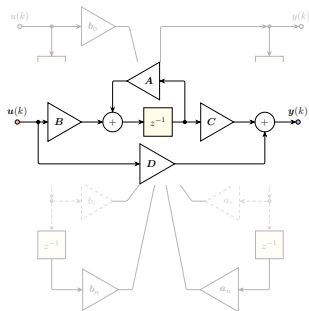
$$\underline{\beta} \leq |H(e^{j\omega})| \leq \overline{\beta}, \quad \forall \omega \in [\omega_1, \omega_2] \subseteq [0, \pi]$$

# Filter evaluation



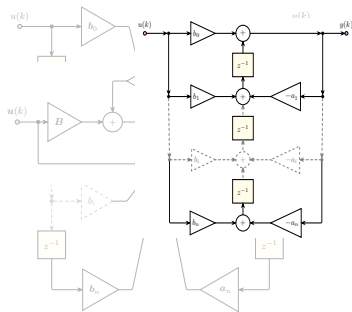
- $$y(k) = \sum_{i=0}^n b_i u(k-i) - \sum_{i=1}^n a_i y(k-i)$$

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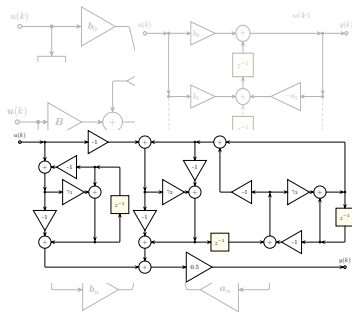
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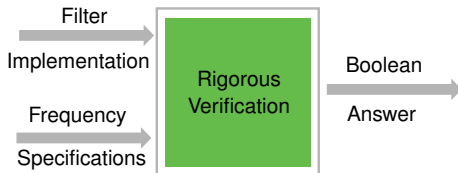
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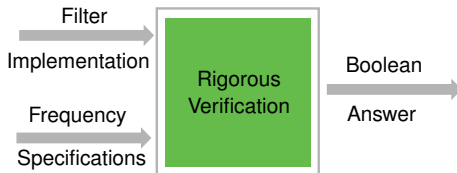
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- ...

Typical algorithm : input  $u(k)$ , state  $\mathbf{x}(k)$ , output  $y(k)$

# Goal: verify an implemented filter



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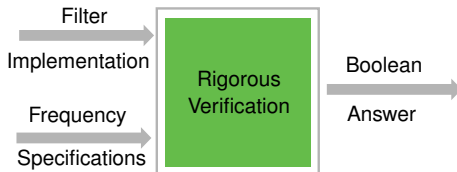
Existing approaches:

- simulations
- approximate magnitude response

Our reliable approach:

- no simulations, only proofs
- rational and interval arithmetic

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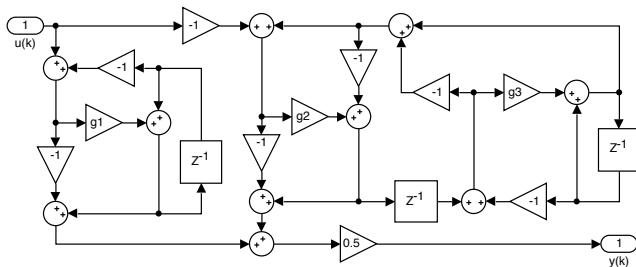
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- no simulations, only proofs
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We use Computer Arithmetic to make Signal Processing rigorous.

# Example

## Filter:



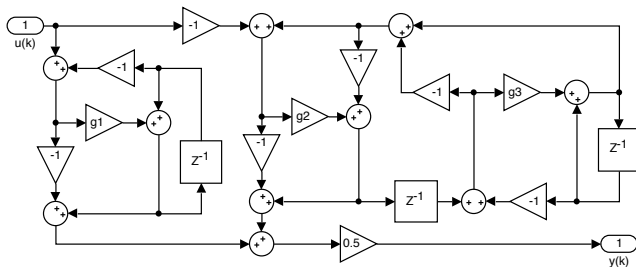
$$g_1 = 89 \cdot 2^{-8}$$

$$g_2 = 43 \cdot 2^{-7}$$

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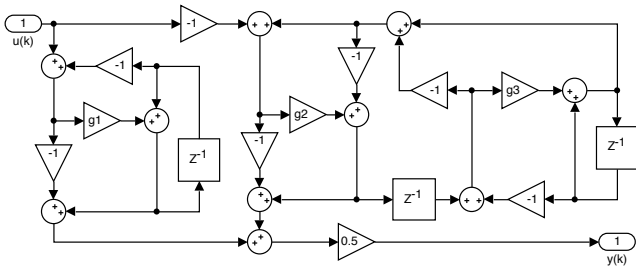
## Specifications:

$$\begin{cases} 1\text{dB} \leq |H(e^{j\omega})| \leq 3\text{dB} & \forall \omega \in [0, \frac{1}{10}\pi] & (\text{passband}) \\ |H(e^{j\omega})| \leq -20\text{dB} & \forall \omega \in [\frac{3}{10}\pi, \pi] & (\text{stopband}) \end{cases}$$



## Example

Filter:



$$g_1 = 89 \cdot 2^{-8}$$

$$g_2 = 43 \cdot 2^{-7}$$

$$g_3 = 11 \cdot 2^{-7}$$

### Specifications:

$$\begin{cases} 10^{\frac{1}{20}} \leq |H(e^{i\omega})| \leq 10^{\frac{3}{20}} & \forall \omega \in [0, \frac{1}{10}\pi] \quad (\text{passband}) \\ |H(e^{i\omega})| \leq 10^{-\frac{20}{20}} & \forall \omega \in [\frac{3}{10}\pi, \pi] \quad (\text{stopband}) \end{cases}$$

### Transfer Function:

$$H(z) = \frac{\sum_{i=0}^n b_i z^{-i}}{\sum_{i=0}^n a_i z^{-i}}$$



# Transfer function verification

Need to show that  $\forall z = e^{j\omega}, \omega \in \Omega \subset [0, \pi]$

$$\underline{\beta} \leq |H(z)| \leq \overline{\beta}$$

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We have that

$$|H(z)|^2 = \frac{|b(z)|^2}{|a(z)|^2} = \frac{b(z)\overline{b(\overline{z})}}{a(z)\overline{a(\overline{z})}} = \frac{b(z)b(\frac{1}{\overline{z}})}{a(z)a(\frac{1}{\overline{z}})} =: \frac{v(z)}{w(z)},$$

$v(z)$  and  $w(z)$  have real coefficients.

# Reducing the problem to a real rational function

$$\underline{\beta}^2 \leq \frac{v(z)}{w(z)} \leq \overline{\beta}^2$$

$$z = e^{j\omega}$$
$$\forall \omega \in \Omega \subseteq [0, \pi]$$

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We don't need to deal with complex variables

Change of variable:  $t = \tan \frac{\omega}{2}$

$$z = e^{j\omega} = \cos \omega + j \sin \omega$$

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$$z = e^{j\omega} = \frac{1 - t^2}{1 + t^2} + j \frac{2t}{1 + t^2}$$

# Reducing the problem to a real rational function

$$\underline{\beta}^2 \leq \frac{v(z)}{w(z)} \leq \overline{\beta}^2$$

$$\underline{\beta}^2 \leq \frac{v\left(\frac{1-t^2}{1+t^2} + j\frac{2t}{1+t^2}\right)}{w\left(\frac{1-t^2}{1+t^2} + j\frac{2t}{1+t^2}\right)} \leq \overline{\beta}^2$$

$$z = e^{j\omega}$$
$$\forall \omega \in \Omega \subseteq [0, \pi]$$

↓

$$t = \tan \frac{\omega}{2}$$
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# Reducing the problem to a real rational function

$$\underline{\beta}^2 \leq \frac{v(z)}{w(z)} \leq \overline{\beta}^2$$

$$\underline{\beta}^2 \leq \underbrace{\frac{r(t) + j\mathfrak{K}(t)}{s(t) + j\mathfrak{U}(t)}}_{\in \mathbb{R} \text{ due to } |H|^2} \leq \overline{\beta}^2$$



Polynomials  $r, s, \mathfrak{K}, \mathfrak{U} \in \mathbb{R}[x]$

$$z = e^{j\omega}$$
$$\forall \omega \in \Omega \subseteq [0, \pi]$$

$\downarrow$

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Now we work only with reals.

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$$\downarrow$$
$$t = \tan \frac{\omega}{2}$$
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Mapping  $t = \tan \frac{\omega}{2}$  maps  $\omega$  onto the whole  $\mathbb{R}$

Change of variable:  $\xi = \frac{t+2-\sqrt{t^2+4}}{2t}$

# Reducing the problem to a real rational function

$$\underline{\beta}^2 \leq \frac{v(z)}{w(z)} \leq \overline{\beta}^2$$

$$\underline{\beta}^2 \leq \frac{r(t)}{s(t)} \leq \overline{\beta}^2$$

$$\underline{\beta}^2 \leq \frac{r(\frac{1-2\xi}{\xi(1-\xi)})}{s(\frac{1-2\xi}{\xi(1-\xi)})} \leq \overline{\beta}^2$$

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$$\forall \xi \in \Xi \subseteq [0, 1]$$

We compute the PGCD( $p, q$ ) with a rigorous heuristic of Char et al.

# Reducing the verification problem to showing the non-negativity of a polynomial

Need to show  $\forall \xi \in \Xi \subseteq [0, 1]$  that

$$\underline{\beta}^2 \leq \frac{p(\xi)}{q(\xi)} \leq \overline{\beta}^2$$

# Reducing the verification problem to showing the non-negativity of a polynomial

Need to show  $\forall \xi \in \Xi \subseteq [0, 1]$  that

$$\underline{\beta}^2 - \frac{\underline{\beta}^2 + \overline{\beta}^2}{2} \leq \frac{p(\xi)}{q(\xi)} - \frac{\underline{\beta}^2 + \overline{\beta}^2}{2} \leq \overline{\beta}^2 - \frac{\underline{\beta}^2 + \overline{\beta}^2}{2}$$

# Reducing the verification problem to showing the non-negativity of a polynomial

Need to show  $\forall \xi \in \Xi \subseteq [0, 1]$  that

$$-\frac{\bar{\beta}^2 - \underline{\beta}^2}{2} \leq \frac{p(\xi) - (\underline{\beta}^2 + \bar{\beta}^2) q(\xi)}{2q(\xi)} \leq \frac{\bar{\beta}^2 - \underline{\beta}^2}{2}$$

# Reducing the verification problem to showing the non-negativity of a polynomial

Need to show  $\forall \xi \in \Xi \subseteq [0, 1]$  that

$$-1 \leq \frac{2}{\overline{\beta}^2 - \underline{\beta}^2} \left( \frac{p(\xi) - (\underline{\beta}^2 + \overline{\beta}^2) q(\xi)}{2q(\xi)} \right) \leq 1$$



# Reducing the verification problem to showing the non-negativity of a polynomial

Need to show  $\forall \xi \in \Xi \subseteq [0, 1]$  that

$$-1 \leq \frac{g(\xi)}{h(\xi)} \leq 1$$

# Reducing the verification problem to showing the non-negativity of a polynomial

Need to show  $\forall \xi \in \Xi \subseteq [0, 1]$  that

$$\frac{g^2(\xi)}{h^2(\xi)} \leq 1$$

# Reducing the verification problem to showing the non-negativity of a polynomial

It suffices to show  $\forall \xi \in \Xi \subseteq [0, 1]$  that

$$h^2(\xi) - g^2(\xi) \geq 0$$

# Reducing the verification problem to showing the non-negativity of a polynomial

It suffices to show  $\forall \xi \in \Xi \subseteq [0, 1]$  that

$$f(\xi) \geq 0$$



All these transformations are performed exactly with rational arithmetic.

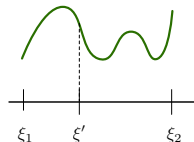
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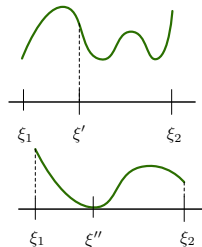
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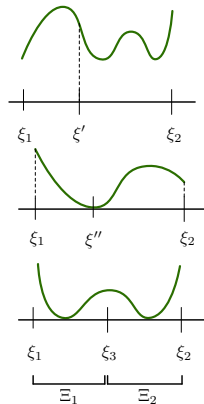
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- (iii) interval  $\Xi$  can be split into subintervals  
s.t. (i) or (ii) are satisfied for every subinterval

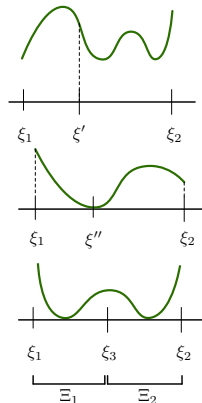




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We use Sollya tool for the implementation

- Number of zeros: Sturm's theorem
- Evaluations: interval multiple precision arithmetic

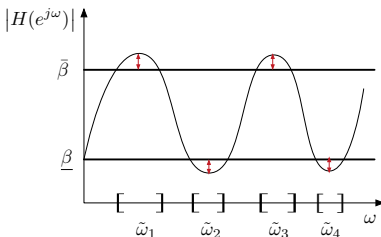
# Wrapping-Up

Does this transfer function verify the frequency specifications?

Yes



No



# Verifying arbitrary filter implementation



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State-Space system:

$$\mathcal{S} \begin{cases} \mathbf{x}(k+1) &= \mathbf{A}\mathbf{x}(k) + \mathbf{b}u(k) \\ y(k) &= \mathbf{c}\mathbf{x}(k) + du(k) \end{cases}$$

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Corresponding Transfer Function:

$$H(z) = \mathbf{c}(z\mathbf{I} - \mathbf{A})^{-1}\mathbf{b} + d$$

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can be approximated using the eigendecomposition of  $\mathbf{A} = \mathbf{V}\mathbf{E}\mathbf{V}^{-1}$

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can be approximated using the eigendecomposition of  $\mathbf{A} = \mathbf{V}\mathbf{E}\mathbf{V}^{-1}$

Need to:

- Compute an approximation  $\hat{H}(z)$  with arbitrary precision (`mpmath`)
- Exhibit a reliable bound on the approximation error  $\left| (H - \hat{H})(e^{j\omega}) \right|$



# Bounding the approximation error

Computing the transfer function  $H(z)$  of the state-space system  $\mathcal{S}$ :

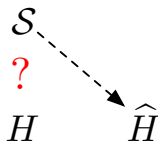
$\mathcal{S}$

?

$H$

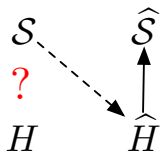
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## Bounding the approximation error

Computing the transfer function  $H(z)$  of the state-space system  $\mathcal{S}$ :



 Transformation from  $\hat{H}$  to  $\hat{\mathcal{S}}$  is exact:

$$\hat{\mathbf{A}} = \begin{pmatrix} -\hat{a}_1 & 1 & & \\ \vdots & & \ddots & \\ \vdots & & & 1 \\ -\hat{a}_n & 0 & \dots & 0 \end{pmatrix} \quad \hat{\mathbf{b}} = \begin{pmatrix} \hat{b}_1 - \hat{a}_1 \hat{b}_0 \\ \vdots \\ \vdots \\ \hat{b}_n - \hat{a}_n \hat{b}_0 \end{pmatrix}$$

$$\hat{\mathbf{c}} = (1 \quad 0 \quad \dots \quad 0) \quad \hat{d} = \hat{b}_0$$

# Bounding the approximation error

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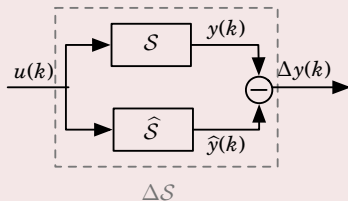
$$\mathcal{S} - \hat{\mathcal{S}} = \Delta\mathcal{S}$$

?

$H \qquad \hat{H}$



Difference of filters is defined as:



# Bounding the approximation error

Computing the transfer function  $H(z)$  of the state-space system  $\mathcal{S}$ :

$$\begin{array}{ccc} \mathcal{S} & - & \hat{\mathcal{S}} = \Delta\mathcal{S} \\ ? & \swarrow & \uparrow \\ H & - & \hat{H} = \Delta H \end{array}$$

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Computing the transfer function  $H(z)$  of the state-space system  $\mathcal{S}$ :

$$\begin{array}{ccc} \mathcal{S} & - & \hat{\mathcal{S}} \\ \textcolor{red}{?} \swarrow & \uparrow & \\ H & - & \hat{H} \end{array} \quad \begin{array}{c} = \\ \\ = \end{array} \quad \begin{array}{c} \Delta\mathcal{S} \\ \textcolor{red}{?} \\ \Delta H \end{array}$$

Relation between  $\Delta\mathcal{S}$  and  $\Delta H$ :

$$\left| \left( H - \hat{H} \right) (e^{j\omega}) \right| \leq \langle\langle \Delta\mathcal{S} \rangle\rangle, \quad \forall \omega \in [0, 2\pi]$$

where  $\langle\langle \Delta\mathcal{S} \rangle\rangle$  is the Worst-Case Peak Gain of the system  $\Delta\mathcal{S}$ .

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where  $\langle \langle \Delta \mathcal{S} \rangle \rangle$  is the Worst-Case Peak Gain of the system  $\Delta \mathcal{S}$ .

We can evaluate  $\langle \langle \Delta \mathcal{S} \rangle \rangle$  with *a priori* error  $\varepsilon$  [ARITH2015].

## Bounding the approximation error

Computing the transfer function  $H(z)$  of the state-space system  $\mathcal{S}$ :

$$\begin{array}{ccc} \mathcal{S} & - & \hat{\mathcal{S}} \\ \textcolor{red}{?} \swarrow & \uparrow & \\ H & - & \hat{H} \end{array} \quad \begin{array}{c} = \\ \\ = \end{array} \quad \begin{array}{c} \Delta\mathcal{S} \\ \textcolor{red}{?} \\ \Delta H \end{array}$$

Relation between  $\Delta\mathcal{S}$  and  $\Delta H$ :

$$\left| \left( H - \hat{H} \right) (e^{j\omega}) \right| \leq \langle\langle \Delta\mathcal{S} \rangle\rangle, \quad \forall \omega \in [0, 2\pi]$$

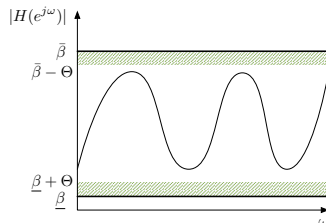
where  $\langle\langle \Delta\mathcal{S} \rangle\rangle$  is the Worst-Case Peak Gain of the system  $\Delta\mathcal{S}$ .

We can evaluate  $\langle\langle \Delta\mathcal{S} \rangle\rangle$  with *a priori* error  $\varepsilon$  [ARITH2015].

We obtain a multiple precision approximation  $\hat{H}$  on the transfer function with a reliable error bound.



# Verifying a LTI filter implementation



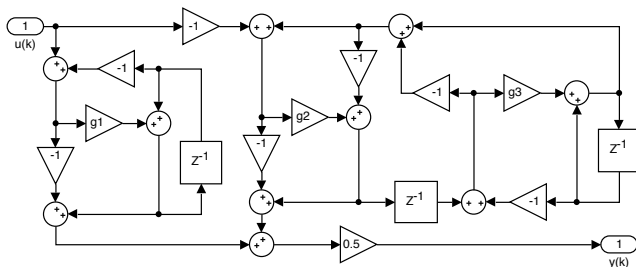
## Taking approximation error into account

Narrow the bounds by  $\Theta = \langle\langle \Delta \mathcal{S} \rangle\rangle + \varepsilon$  and verify the approximation  $\hat{H}(z)$  against updated specifications:

$$\underline{\beta} + \Theta \leq \left| \hat{H}(e^{j\omega}) \right| \leq \bar{\beta} - \Theta, \quad \forall \omega \in \Omega$$

## Numerical results: example 1

### Filter implementation:



$$g_1 = 89 \cdot 2^{-8}$$

$$g_2 = 43 \cdot 2^{-7}$$

$$g_3 = 11 \cdot 2^{-7}$$

### Specifications:

$$\begin{cases} 10^{\frac{1}{20}} \leq |H(e^{i\omega})| \leq 10^{\frac{3}{20}} & \forall \omega \in [0, \frac{1}{10}\pi] \quad (\text{passband}) \\ |H(e^{i\omega})| \leq 10^{-\frac{20}{20}} & \forall \omega \in [\frac{3}{10}\pi, \pi] \quad (\text{stopband}) \end{cases}$$

**Verification result:** implemented filter *passed* the verification against frequency specifications

**Verification time: 1.9 s**

## Numerical results: example 2

**Filter implementation:** 14<sup>th</sup> order bandpass filter

**Specifications:**

$$\left\{ \begin{array}{ll} 0\text{dB} \leq \left| H(e^{i\omega}) \right| \leq & \begin{array}{ll} -80\text{dB} & \forall \omega \in [0, 17\text{kHz}] \quad (\text{stopband}) \\ 1 - 10^{-4}\text{dB} & \forall \omega \in [21\text{kHz}, 25\text{kHz}] \quad (\text{passband}) \\ -80\text{dB} & \forall \omega \in [27\text{kHz}, 30\text{kHz}] \quad (\text{stopband}) \end{array} \end{array} \right.$$

**Verification result:** implemented filter *does not* pass the verification against frequency constraints

**Verification time:** 53 s

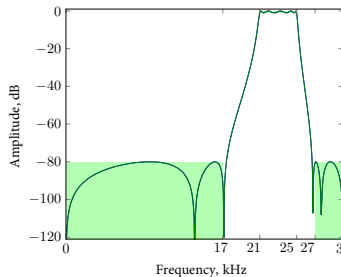
## Numerical results: example 2

**Filter implementation:** 14<sup>th</sup> order bandpass filter

**Verification result:** implemented filter *does not* pass the verification against frequency constraints

**Verification time:** 53 s

**Frequency response:**



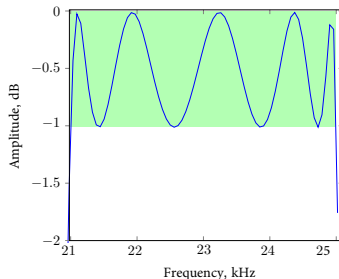
## Numerical results: example 2

**Filter implementation:** 14<sup>th</sup> order bandpass filter

**Verification result:** implemented filter *does not* pass the verification against frequency constraints

**Verification time:** 53 s

**Frequency response:**



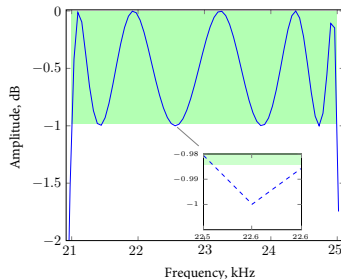
## Numerical results: example 2

**Filter implementation:** 14<sup>th</sup> order bandpass filter

**Verification result:** implemented filter *does not* pass the verification against frequency constraints

**Verification time:** 53 s

**Frequency response:**



## Numerical results: example 3

Verification of the 9<sup>th</sup> order FIR filter from Silviu's presentation:

- coefficients quantized to 7 bits
- error on the transfer function is roughly 0.047
- passband  $[0, \frac{1}{3}\pi]$ , stopband  $[0.5\pi, \pi]$

## Numerical results: example 3

Verification of the 9<sup>th</sup> order FIR filter from Silviu's presentation:

- coefficients quantized to 7 bits
- error on the transfer function is roughly 0.047
- passband  $[0, \frac{1}{3}\pi]$ , stopband  $[0.5\pi, \pi]$

### Result:

Overall check okay: true

Computing this result took 7209ms



# Conclusion and Perspectives

## Conclusion:

- Reliable *a posteriori* verification of any implemented linear filter
- Multiple precision approximation of any filter's transfer function
- Approximation errors of the transfer function are fully accounted for
- Algorithm implemented using a combination of rational and interval arithmetic in Sollya
- Use-cases: verification and comparison of implementations, verification on design-stage, verification of design methods

## Perspectives:

- Improve algorithm timings
- Prove our implementation with Coq
- Exploit information on the problematic frequencies for more robust design and implementation

Thank you!  
Questions?

# Transfer Function of a State-Space

Transfer function of a single-input single-output state-space  $\mathcal{S}$ :

$$H(z) = \mathbf{c}(z\mathbf{I} - \mathbf{A})^{-1}\mathbf{b} + d$$

Using the eigendecomposition  $\mathbf{A} = \mathbf{V}\mathbf{E}\mathbf{V}^{-1}$ :

$$H(z) = \frac{P(z)}{Q(z)} + d$$

$$P(z) = \sum_{i=1}^n (\mathbf{c}\mathbf{V})_i (\mathbf{V}^{-1}\mathbf{b})_i \prod_{j \neq i} (z - \lambda_j)$$

$$Q(z) = \prod_{j=1}^n (z - \lambda_j)$$

We compute an approximation  $\hat{H}(z)$  in Multiple Precision arithmetic.

# Numerical results

**Input:** four realizations of the same filter

**Problem:** verify realizations after coefficient quantization to 32/16/8 bits

**Results:**

	wordlength	32	16	8
DFIlt	margin	✓	unstable	unstable
	time	12.49s	-	-
$\rho$ DFIlt	margin	✓	✓	4.68e-3 dB
	time	13.12s	4.19s	104.01s
State-Space Balanced	margin	6.16e-10 dB	✓	6.71e-1 dB
	time	12.27s	18.18s	92.05s
Lattice Wave	margin	3.80e-10 dB	✓	1.73e-2 dB
	time	920.88s	4.58s	200.83s

## Numerical results:

**Input:** four simple frequency specifications

**Problem:** Verify and compare transfer function design methods.

**Results:** comparison of SciPy in Python and Matlab

		Butterworth	Chebyshev	Elliptic
		margin (dB)	margin (dB)	margin (dB)
lowpass	Matlab	1.29e-17	7.93e-17	✓
	SciPy	2.14e-15	4.48e-2	4.48e-2
highpass	Matlab	2.77e-16	6.94e-17	4.48e-2
	SciPy	3.02e-15	2.29e-16	4.48e-2
bandpass	Matlab	3.04e-17	✓	✓
	SciPy	✓	4.48e-2	4.48e-2
bandstop	Matlab	4.59e-16	3.09e-15	✓
	SciPy	✓	6.36e-15	7.02e-6

# Verification of specifications

## Sturm's technique

Sturm's sequence is a sequence of polynomials  $p_0(x), \dots, p_m(x)$ :

$$p_0(x) = p(x)$$

$$p_1(x) = p'(x)$$

$$p_2(x) = -\text{rem}(p_0, p_1) = p_1(x)q_0(x) - p_0(x),$$

$$p_3(x) = -\text{rem}(p_1, p_2) = p_2(x)q_1(x) - p_1(x),$$

...

$$0 = -\text{rem}(p_{m-1}, p_m)$$